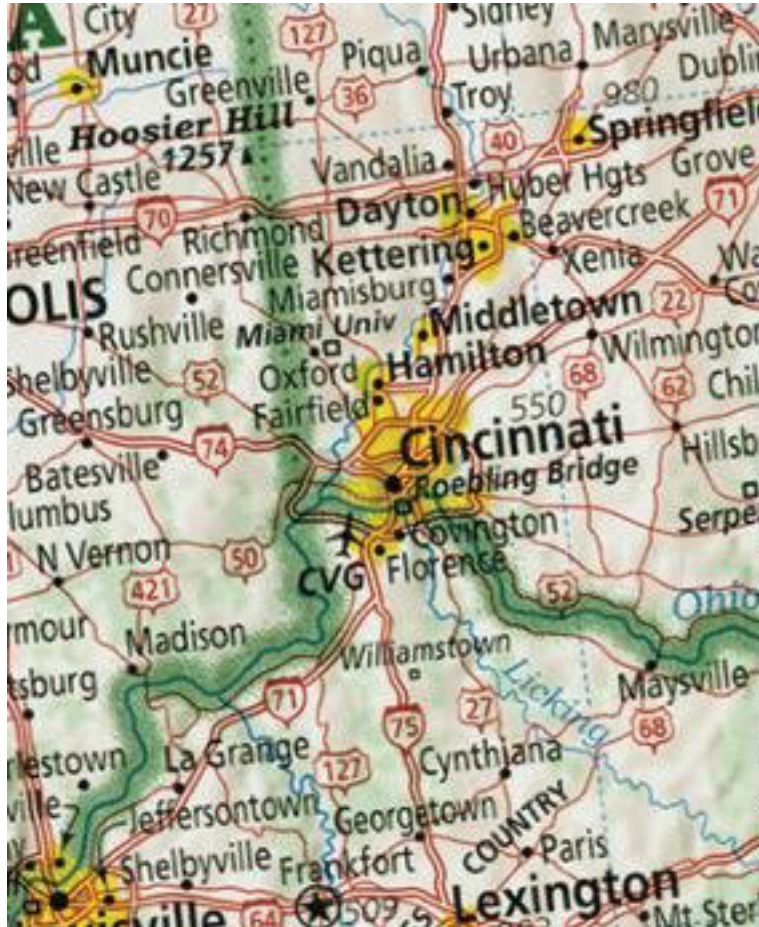


Algorithms for (Dynamic) Map Labeling

joint work with A. Gemsa and B. Niedermann

Map labeling – an old problem



© David Imus

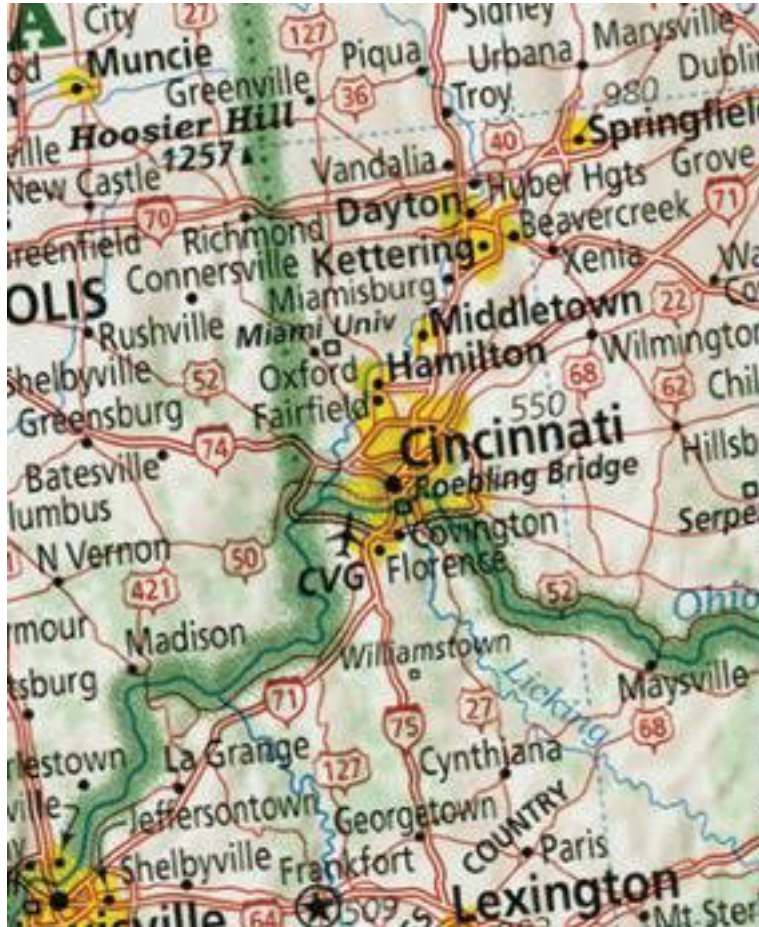
“Poor, sloppy, amateurisch type placement is irresponsible; it spoils even the best image and impedes reading.” (E. Imhof '75)

Cartography has long history and experience with manual label placement in maps.

some placement guidelines:

- next to, over, or under the object
- preferably top right
- avoid covering and overlapping
- clear graphic association
- ...

Map labeling – an old problem



© David Imus

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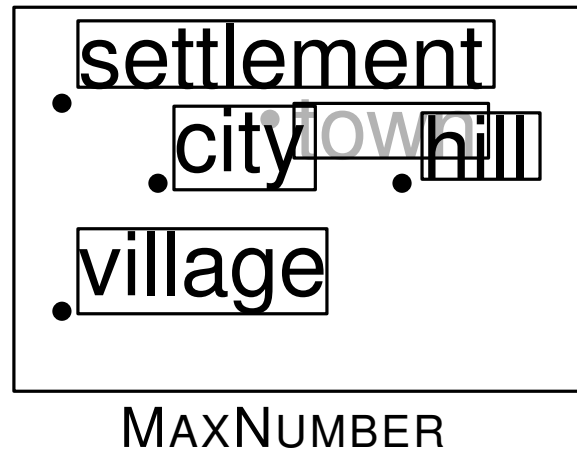
- next to, over, or under the object
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- ...

→ has been translated > 20 years ago into a computational geometry problem for automated label placement

Static geometric labeling models

Input: n points in the plane and for each point a label represented by its bounding box

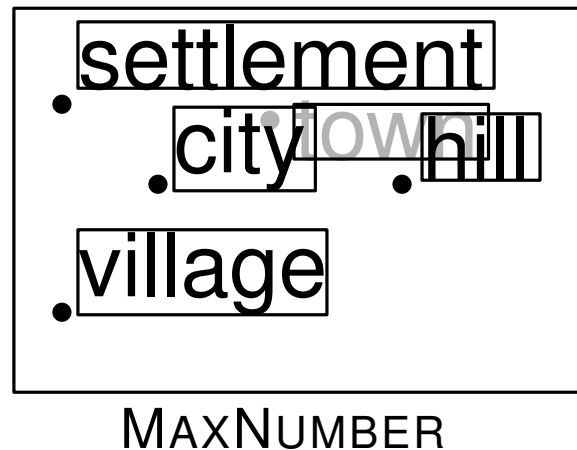
Goal: find a feasible* label placement for a **maximum subset** of the points such that no two labels overlap (MAXNUMBER)



Static geometric labeling models

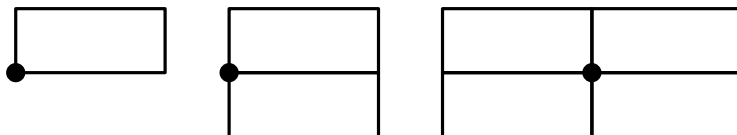
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* What is a **feasible** placement?

discrete models

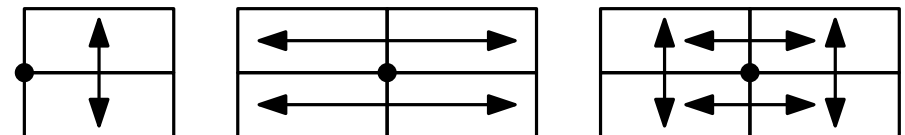


1P

2P

4P

slider models



1S

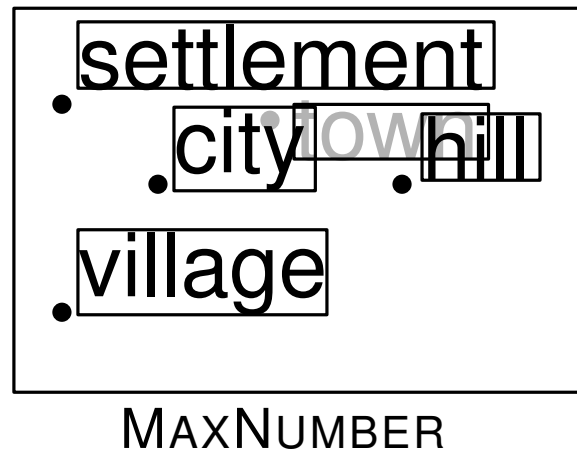
2S

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Static geometric labeling models

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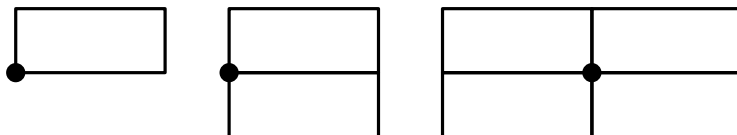
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NP-hard in almost all models

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discrete models

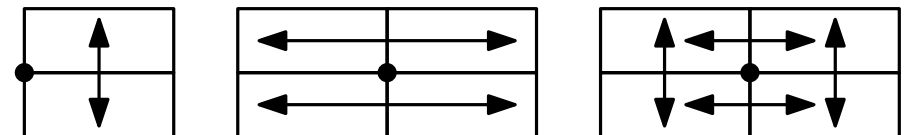


1P

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slider models



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The era of dynamic maps

Most maps today are no longer static and general-purpose but dynamic and individualized.



The era of dynamic maps

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map view moves continuously as the user

- zooms
- translates
- rotates
- tilts

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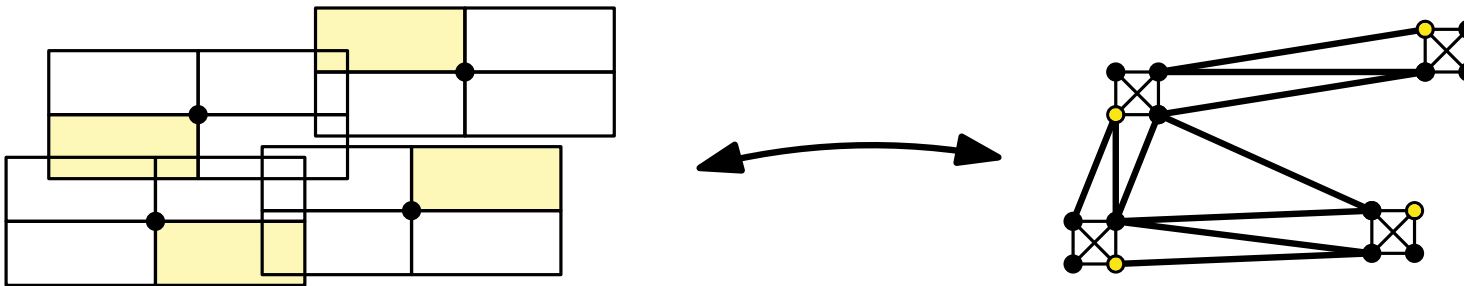
layout and labeling must adapt to dynamic map movement

→ continuous map generalization

→ **continuous map labeling**

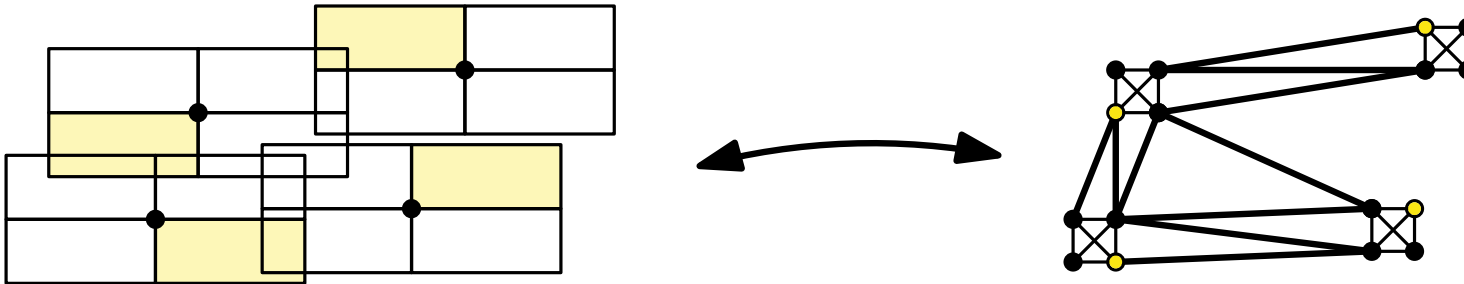
Dynamic map labeling – a new problem?

Most heuristic **static** approaches use a conflict graph to model overlaps and then use some strategy to find a large independent set of labels.



Dynamic map labeling – a new problem?

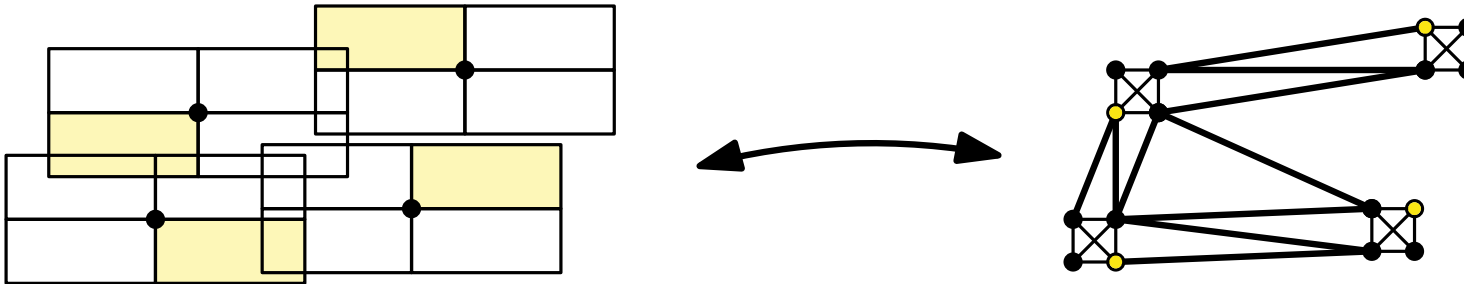
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Adaptation to **dynamic** maps: design practically fast algorithms to label each frame of an animation in real time.

Dynamic map labeling – a new problem?

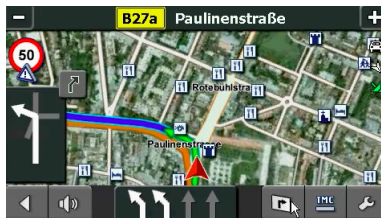
Most heuristic **static** approaches use a conflict graph to model overlaps and then use some strategy to find a large independent set of labels.



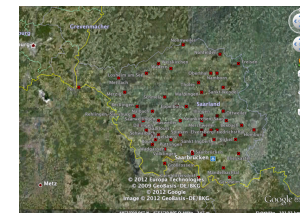
Adaptation to **dynamic** maps: design practically fast algorithms to label each frame of an animation in real time.

Yields fast algorithms, but resulting map animations are often insufficient

- each frame is labeled independently of adjacent frames
- labels tend to show jumping and flickering behaviour
- **temporal coherence** or **consistency** is not considered

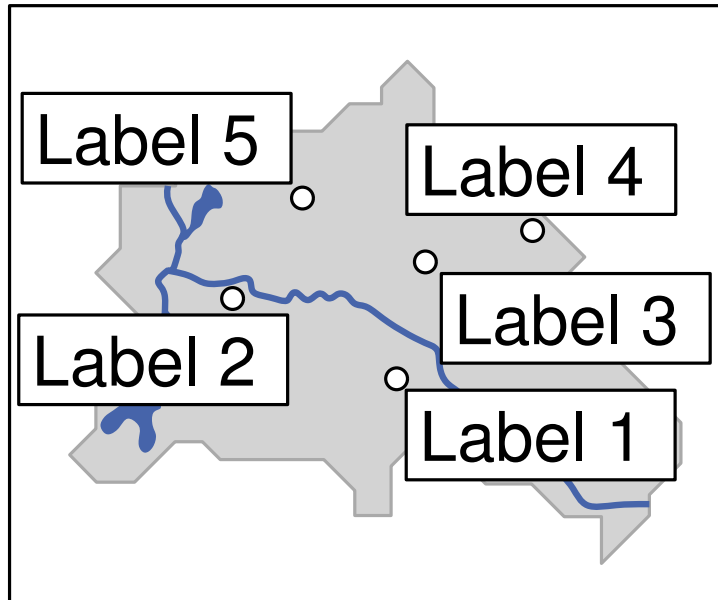


many examples!



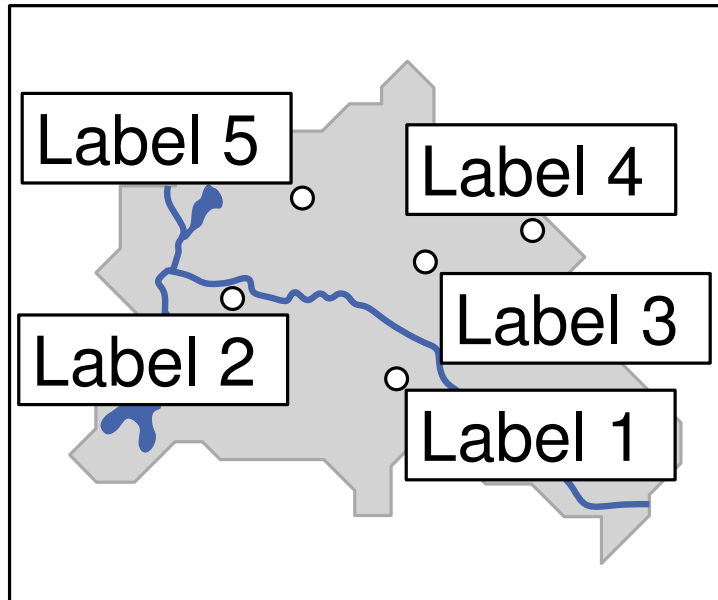
Labels in zoomable maps

labeled map at larger scale

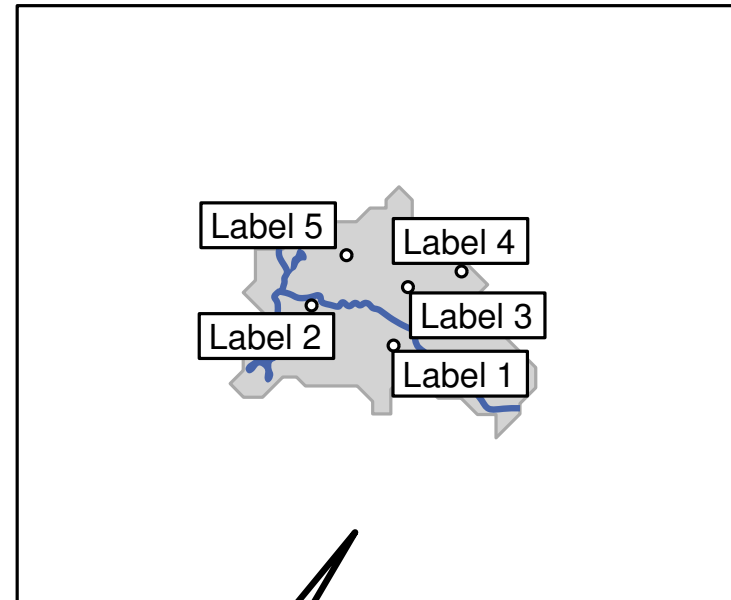


Labels in zoomable maps

labeled map at larger scale



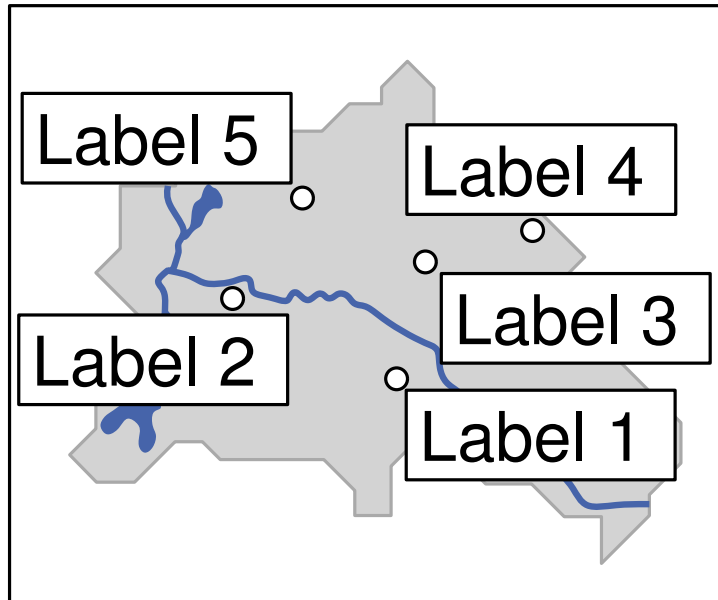
labeled map at smaller scale



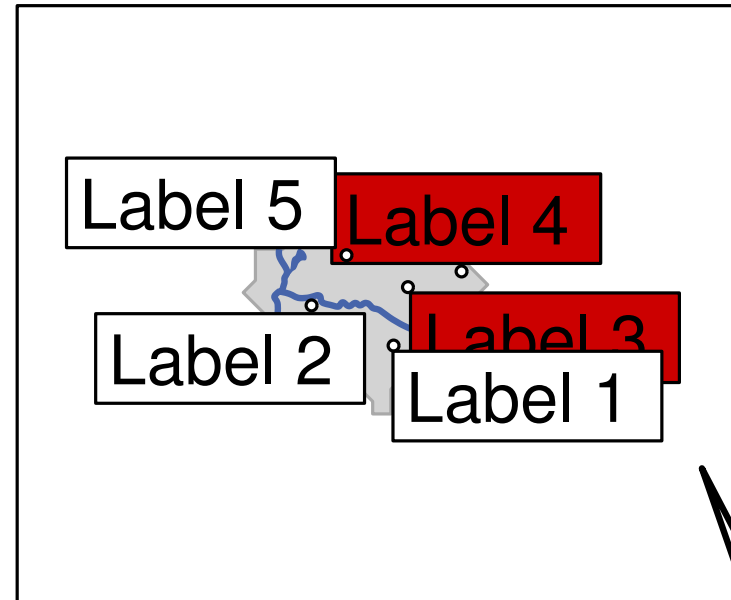
graphical zooming creates tiny labels

Labels in zoomable maps

labeled map at larger scale



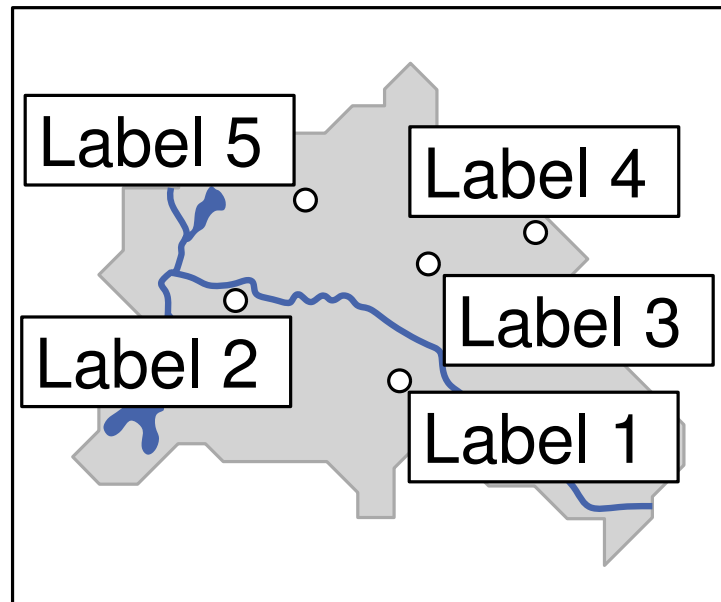
labeled map at smaller scale



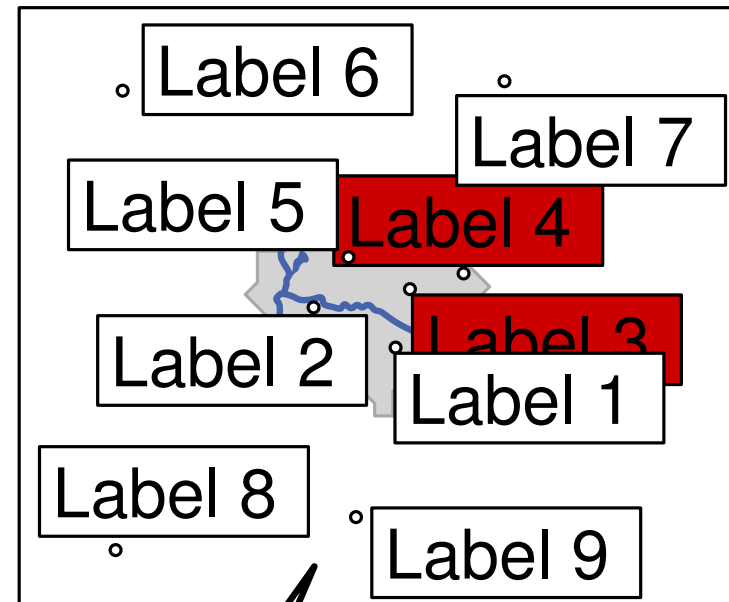
invariant label size creates new conflicts

Labels in zoomable maps

labeled map at larger scale



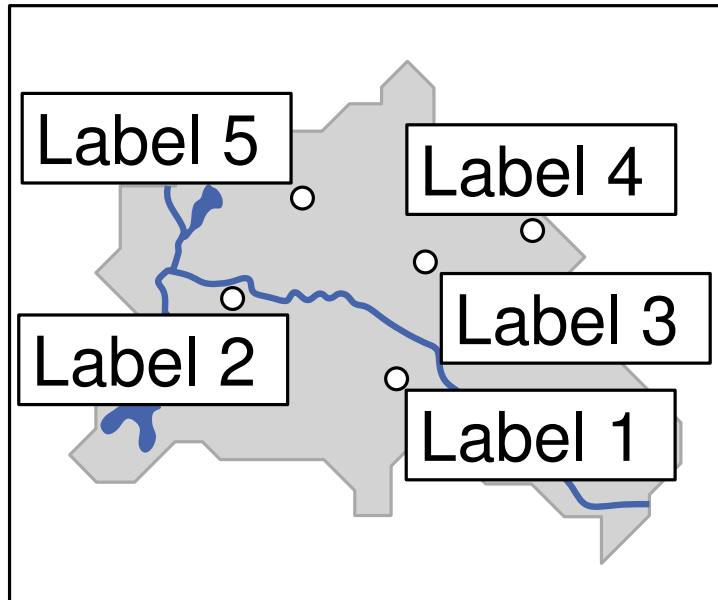
labeled map at smaller scale



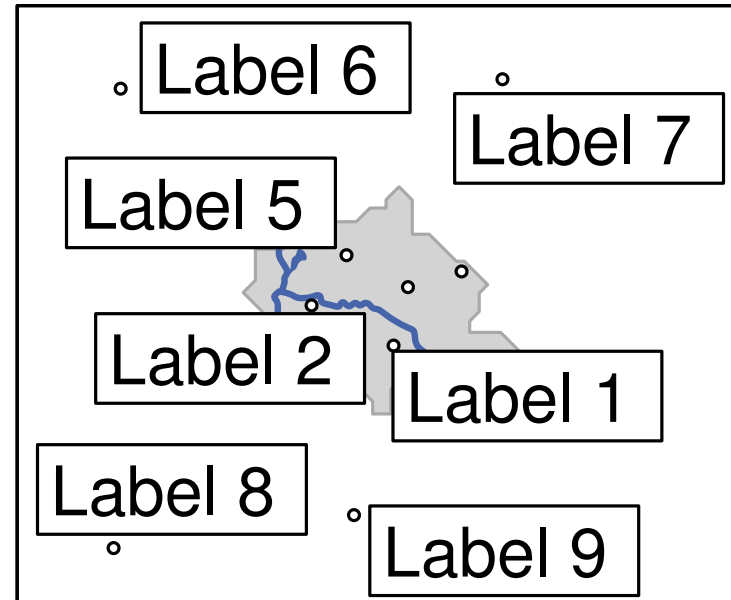
more points become visible

Labels in zoomable maps

labeled map at larger scale



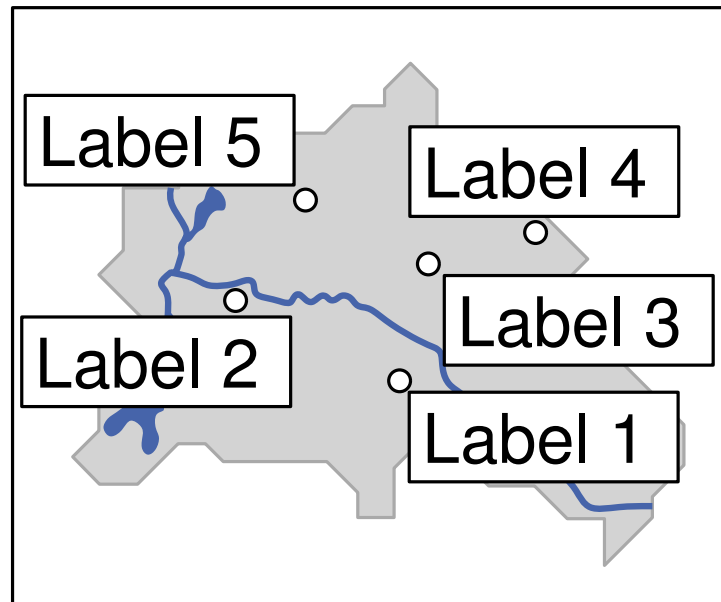
labeled map at smaller scale



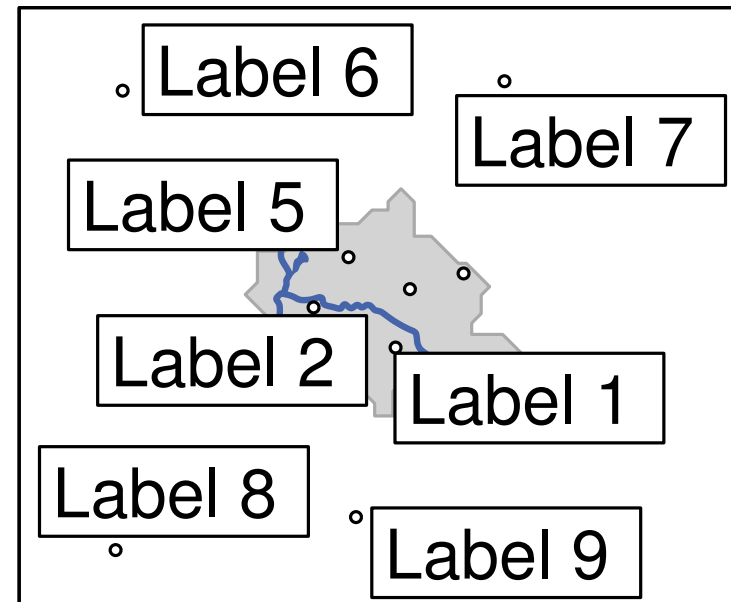
⇒ when zooming out, labels grow relative to the map and new conflicts must be resolved s.t. labels do not jump or flicker

Labels in zoomable maps

labeled map at larger scale



labeled map at smaller scale

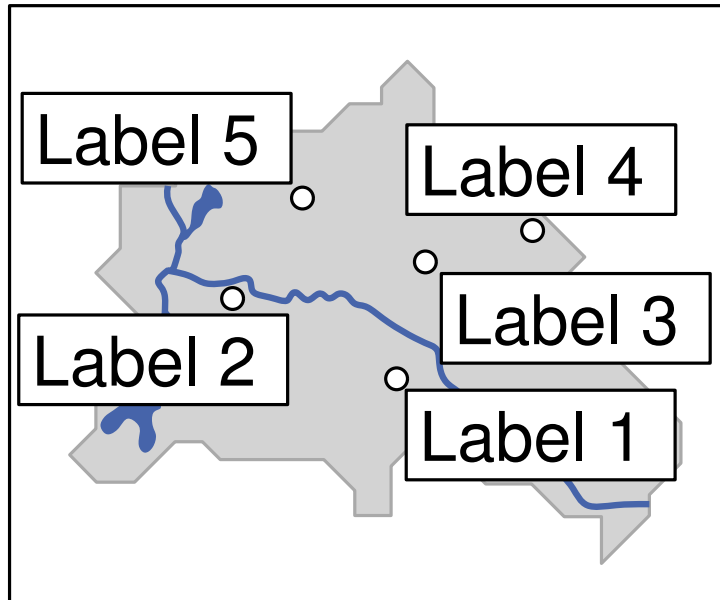


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Techniques: Geometric approximation algorithms

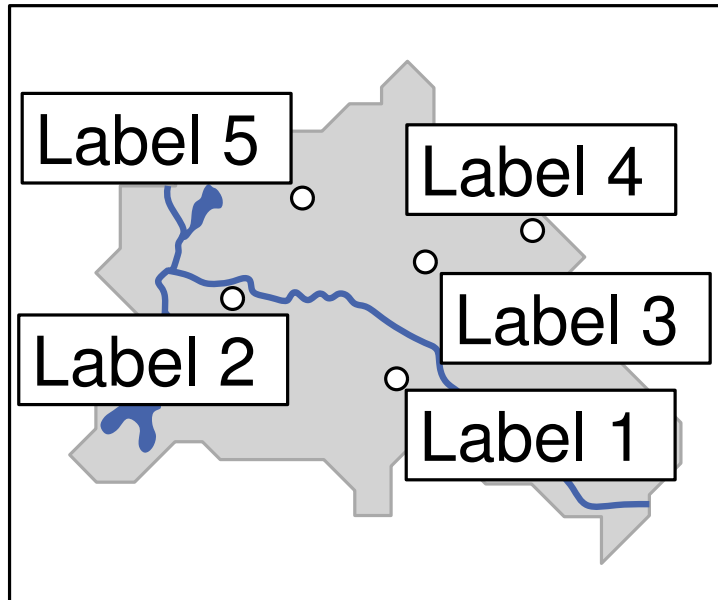
Labels in rotating maps

northern orientation

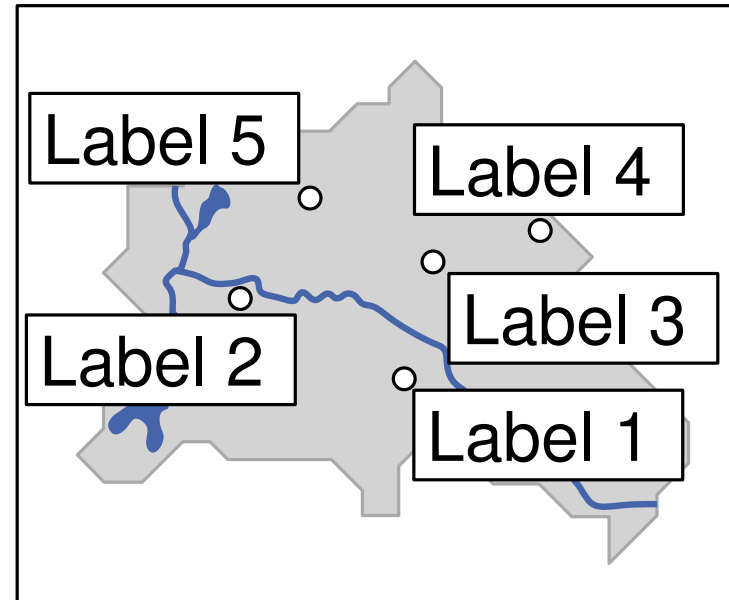


Labels in rotating maps

northern orientation

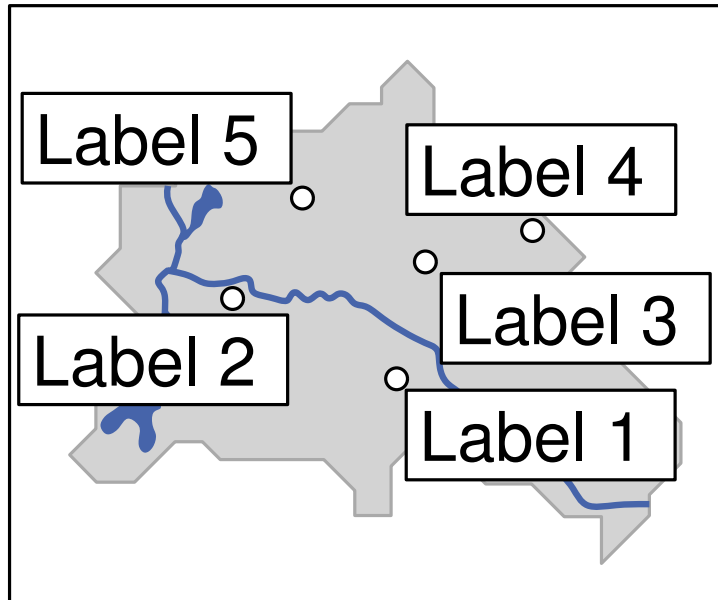


rotated view

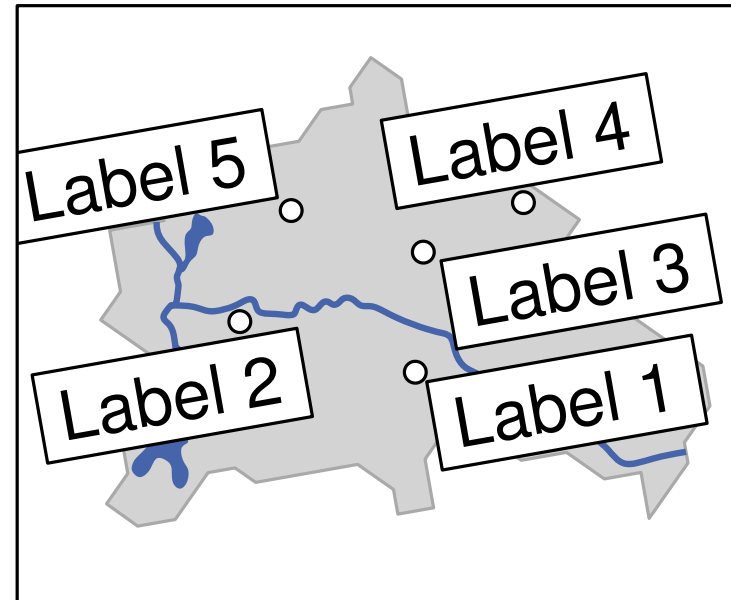


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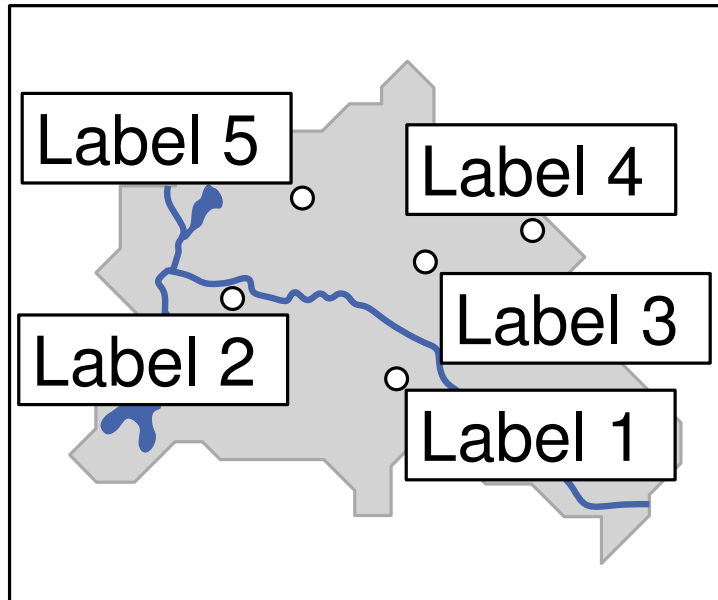


rotated view

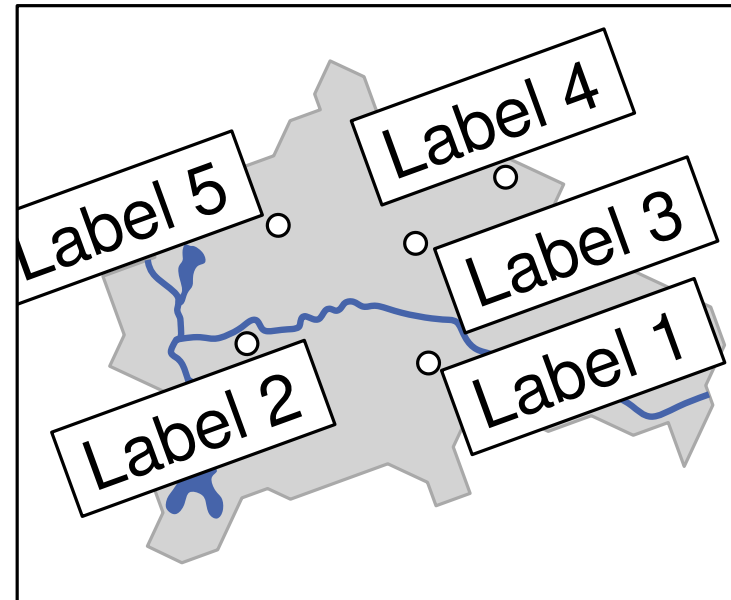


Labels in rotating maps

northern orientation

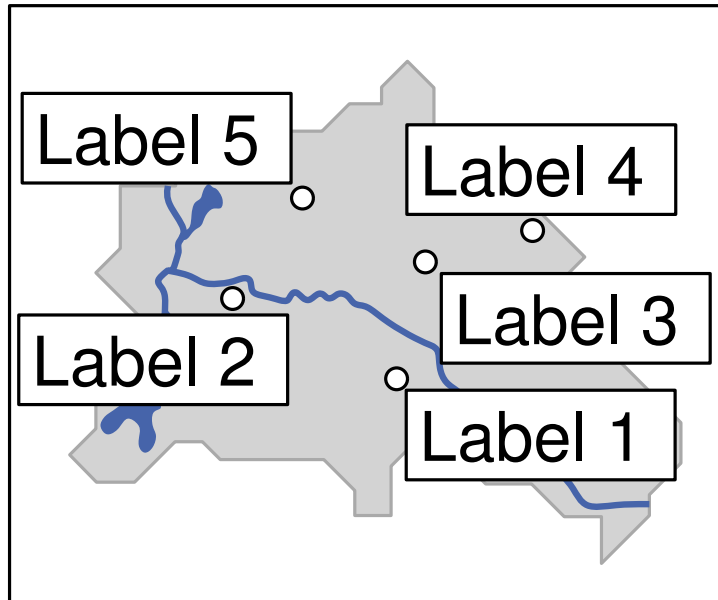


rotated view

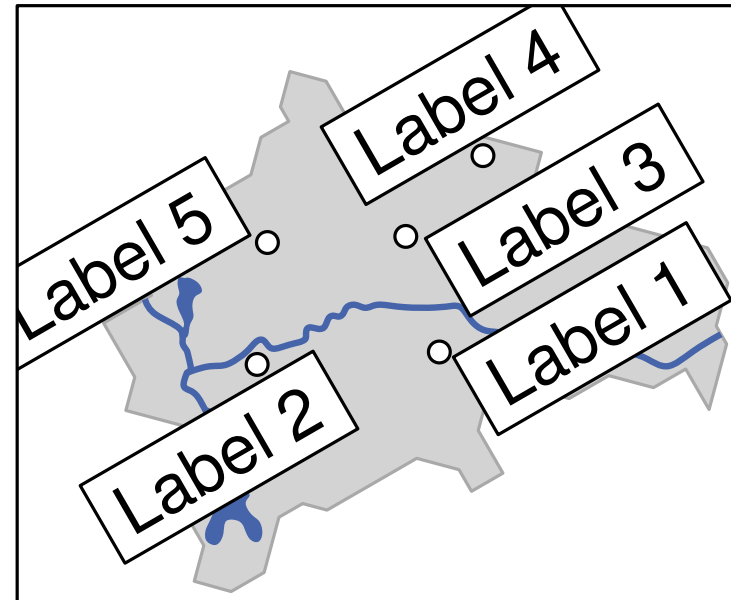


Labels in rotating maps

northern orientation

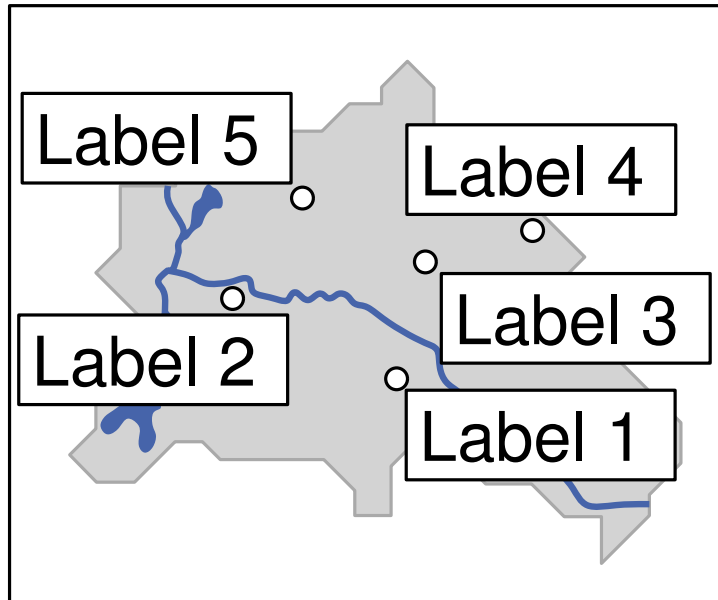


rotated view

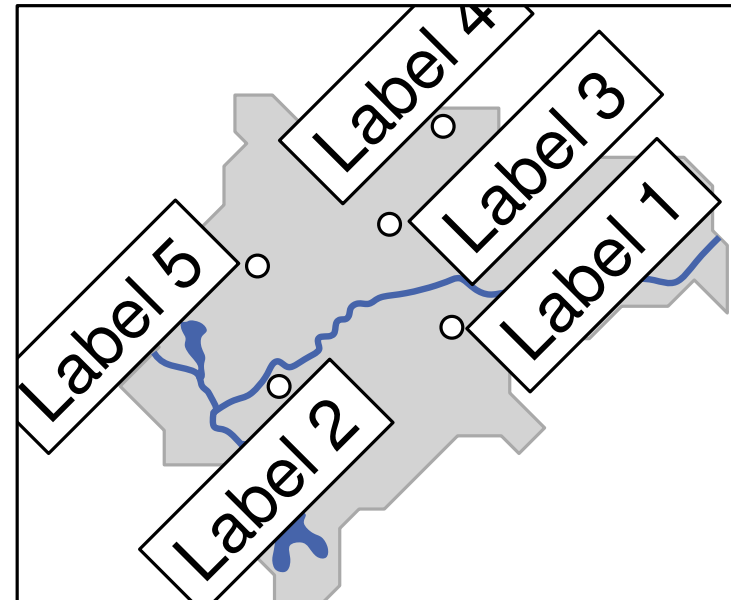


Labels in rotating maps

northern orientation

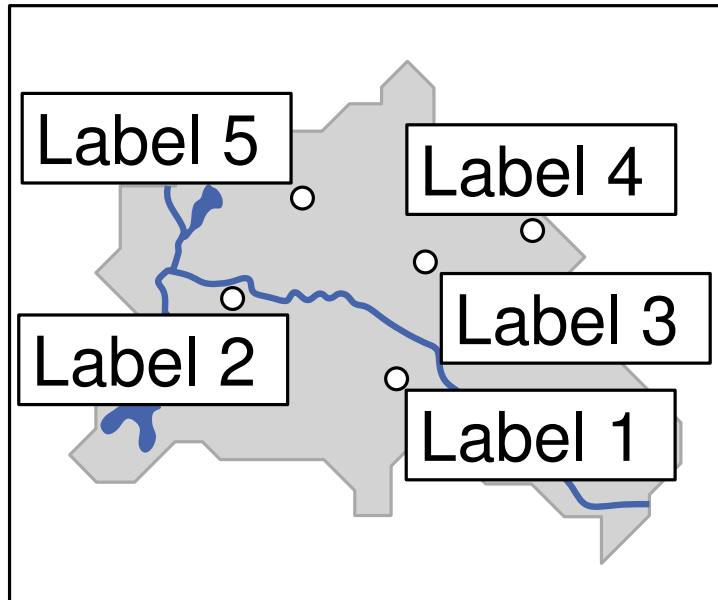


rotated view

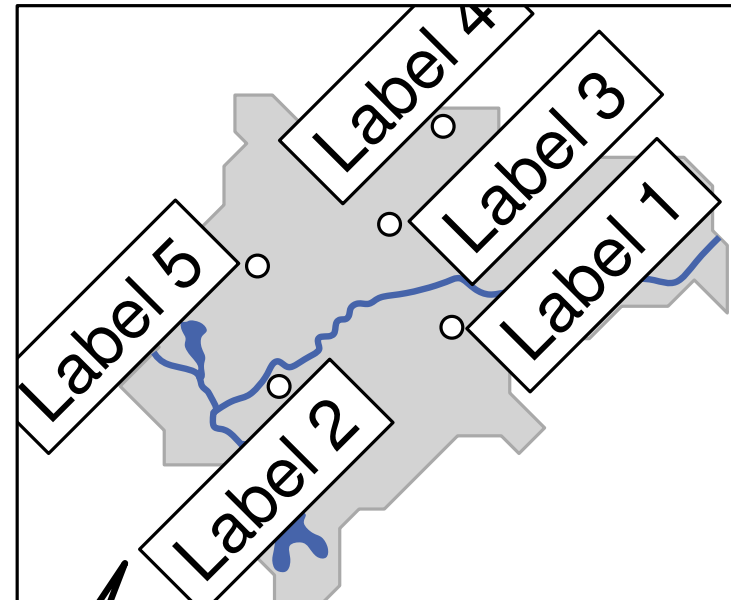


Labels in rotating maps

northern orientation



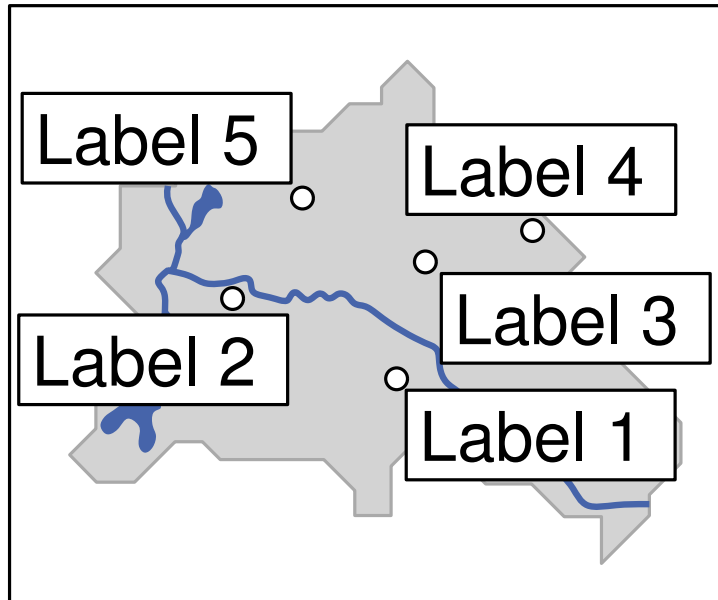
rotated view



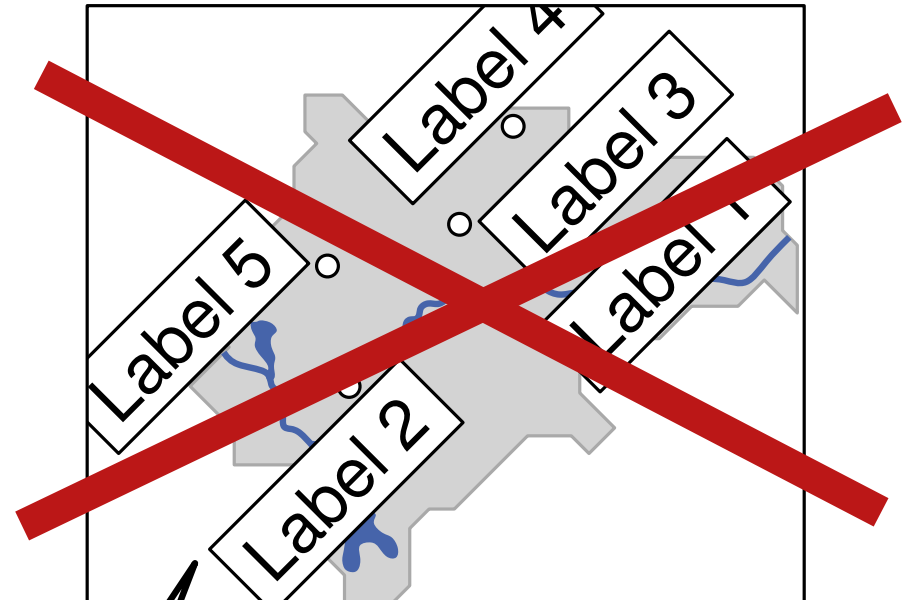
poor readability of map aligned labels

Labels in rotating maps

northern orientation



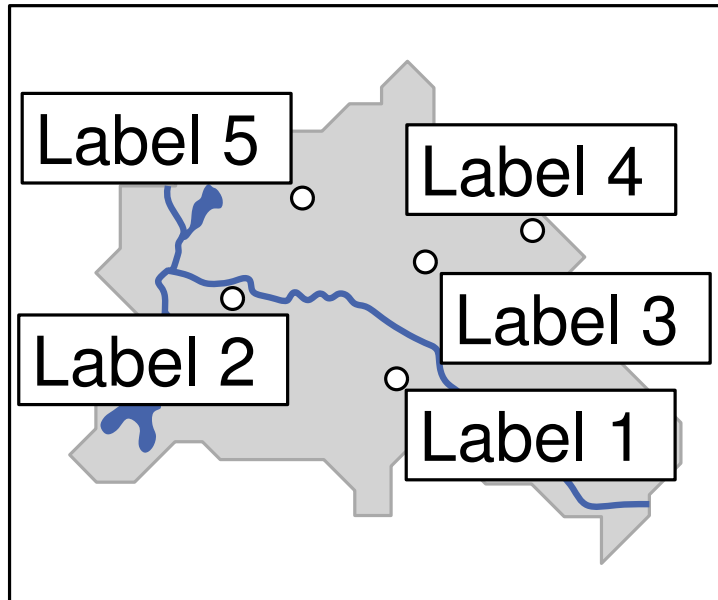
rotated view



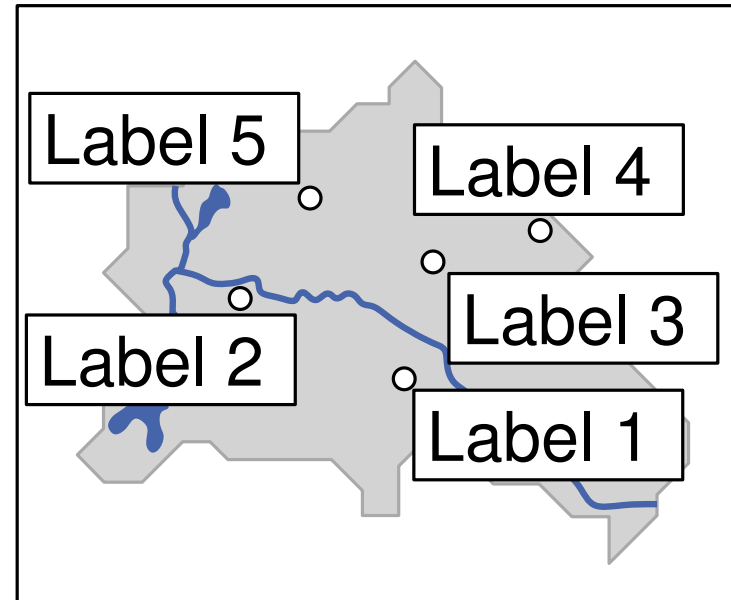
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Labels in rotating maps

northern orientation

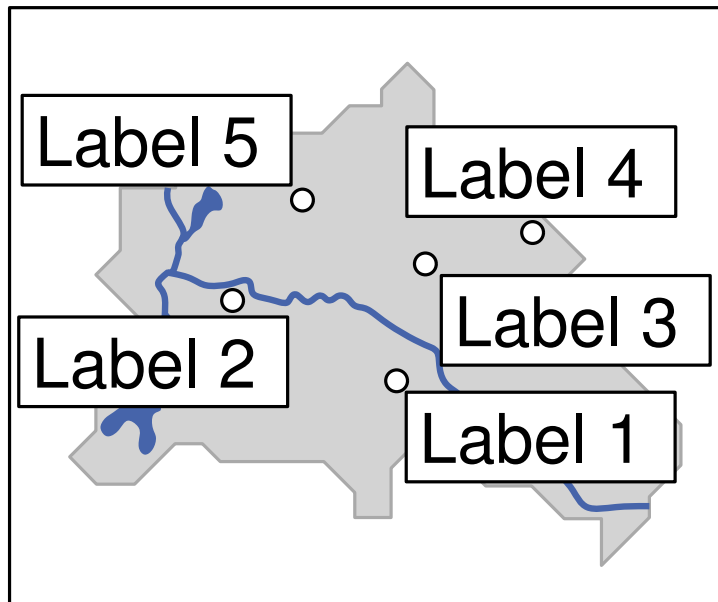


rotated view

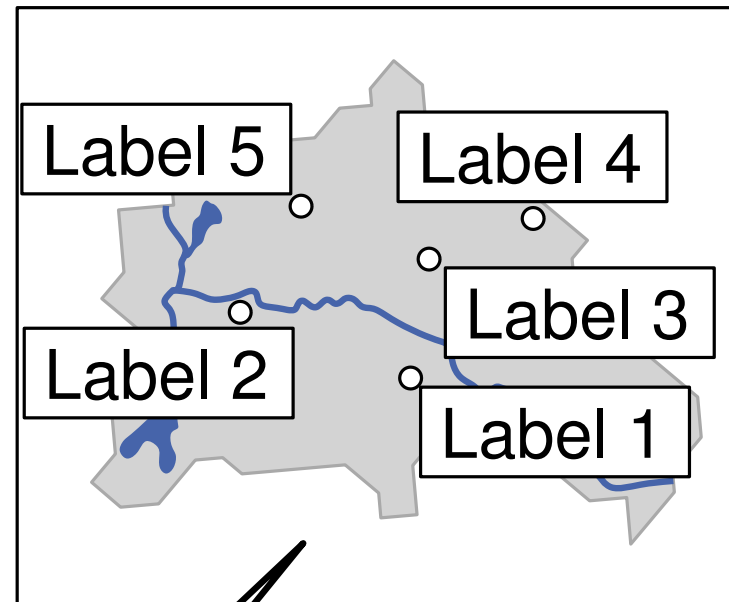


Labels in rotating maps

northern orientation



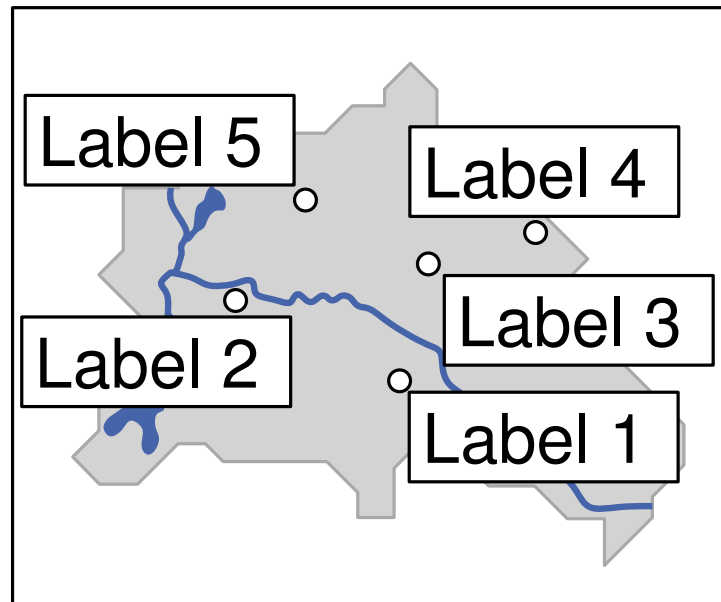
rotated view



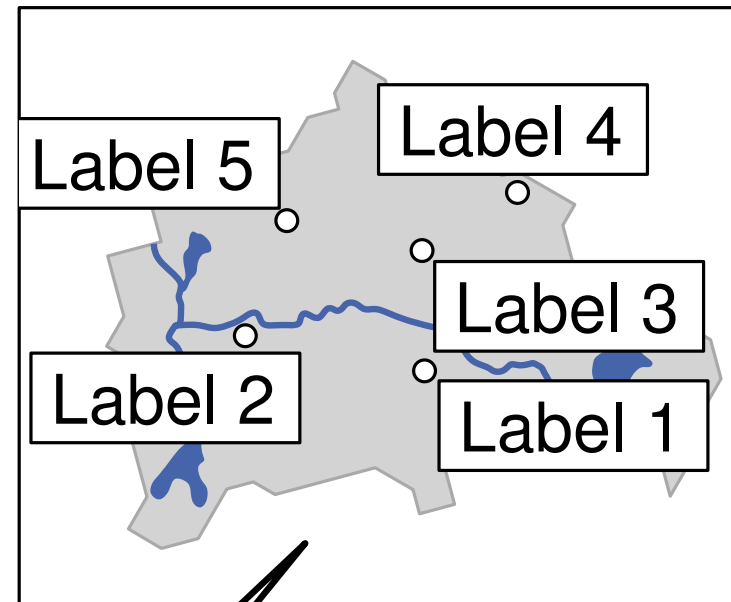
use view-aligned labels instead

Labels in rotating maps

northern orientation



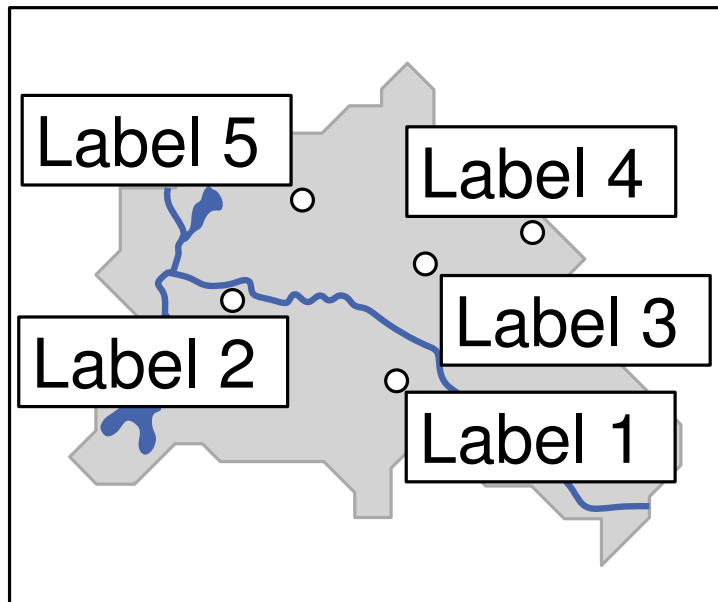
rotated view



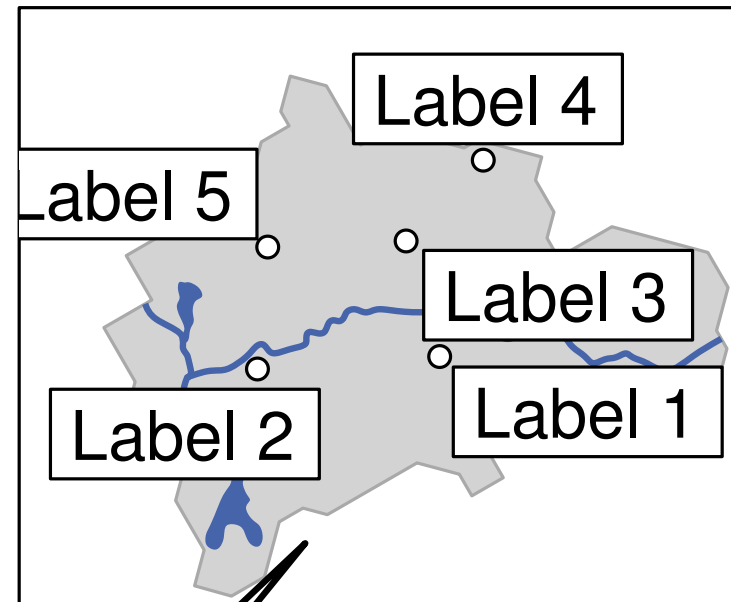
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Labels in rotating maps

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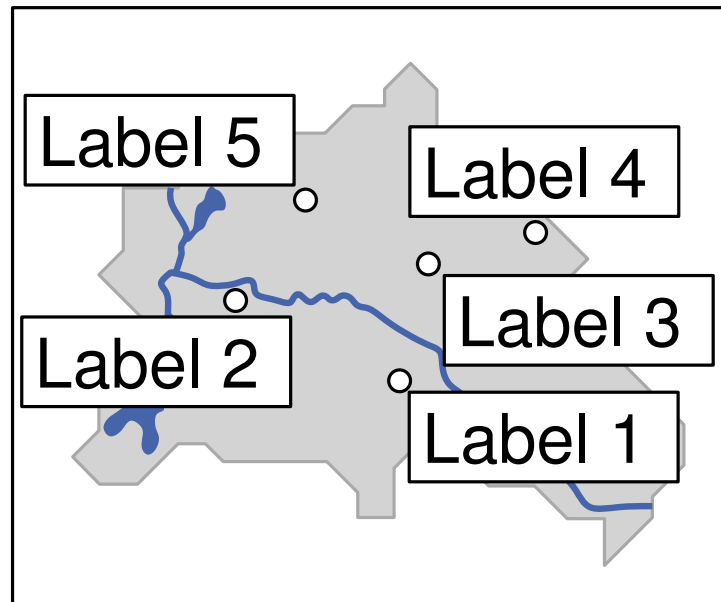
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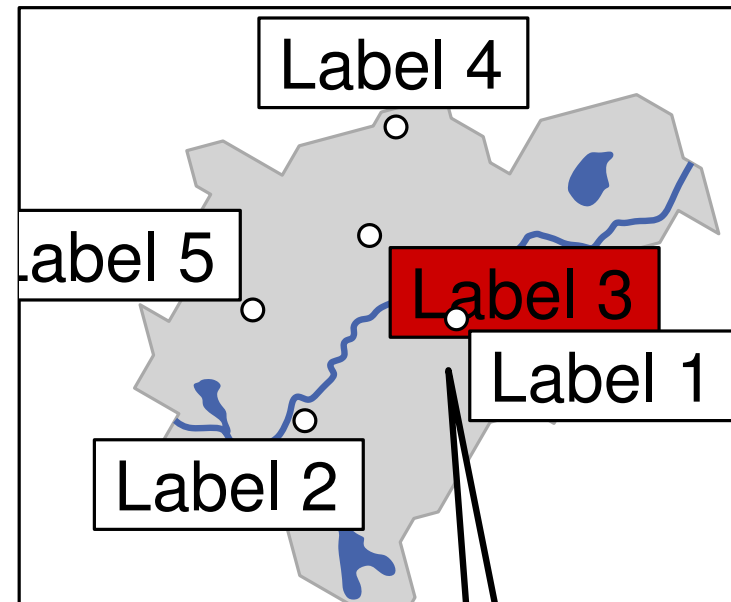
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Labels in rotating maps

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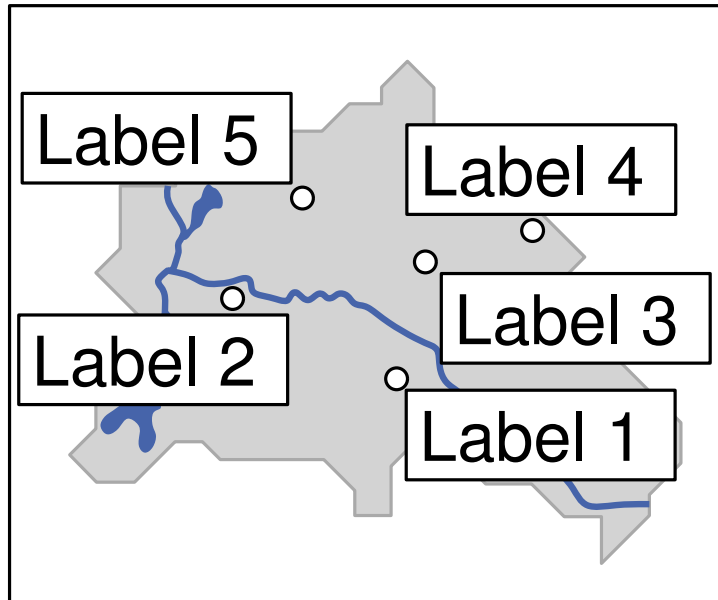
rotated view



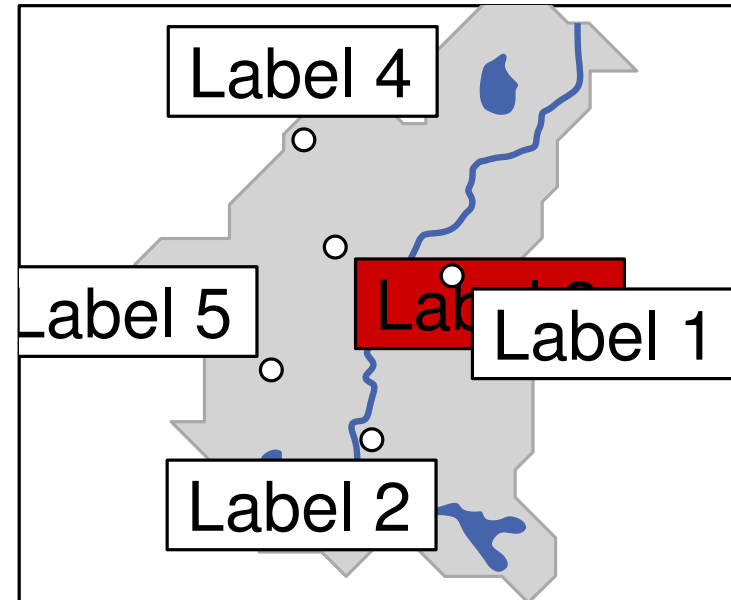
rotation creates new conflicts

Labels in rotating maps

northern orientation



rotated view

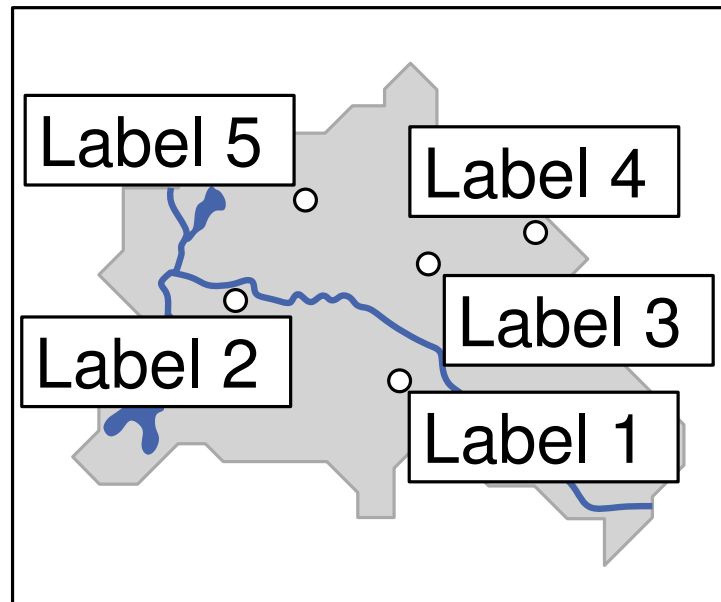


⇒ under rotation, horizontally aligned labels create new conflicts that must be resolved s.t. labels do not jump or flicker

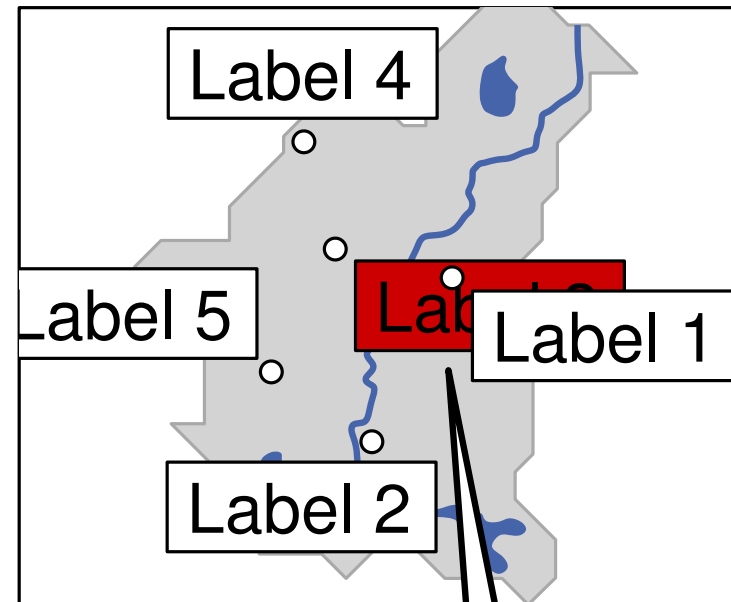
Techniques: approximation via decomposition into geometrically independent and exactly solvable subproblems; heuristics

Labels in rotating maps

northern orientation

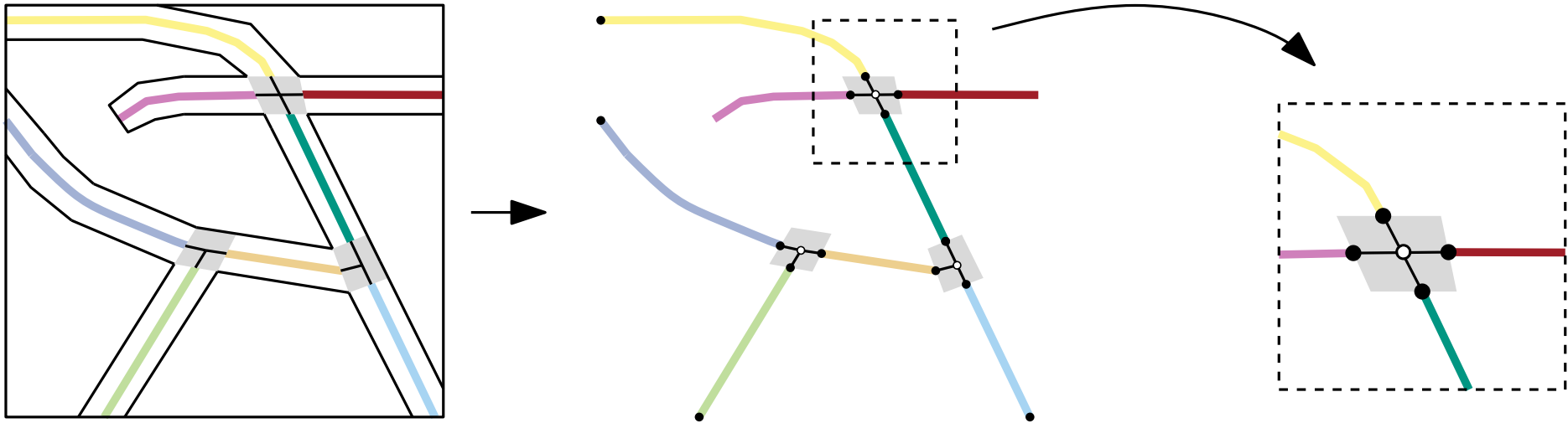


rotated view



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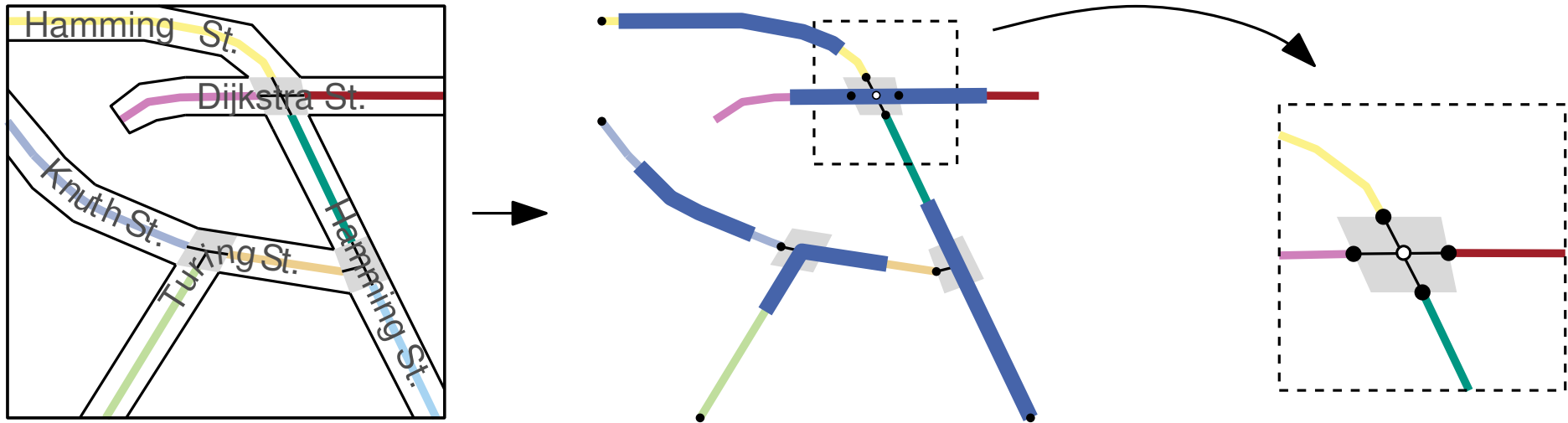
Open problem: (dynamic) road labeling



Model road map as a planar embedded graph.

- Each road section becomes an edge
- *Junctions* are shared resource of multiple roads

Open problem: (dynamic) road labeling



Model road map as a planar embedded graph.

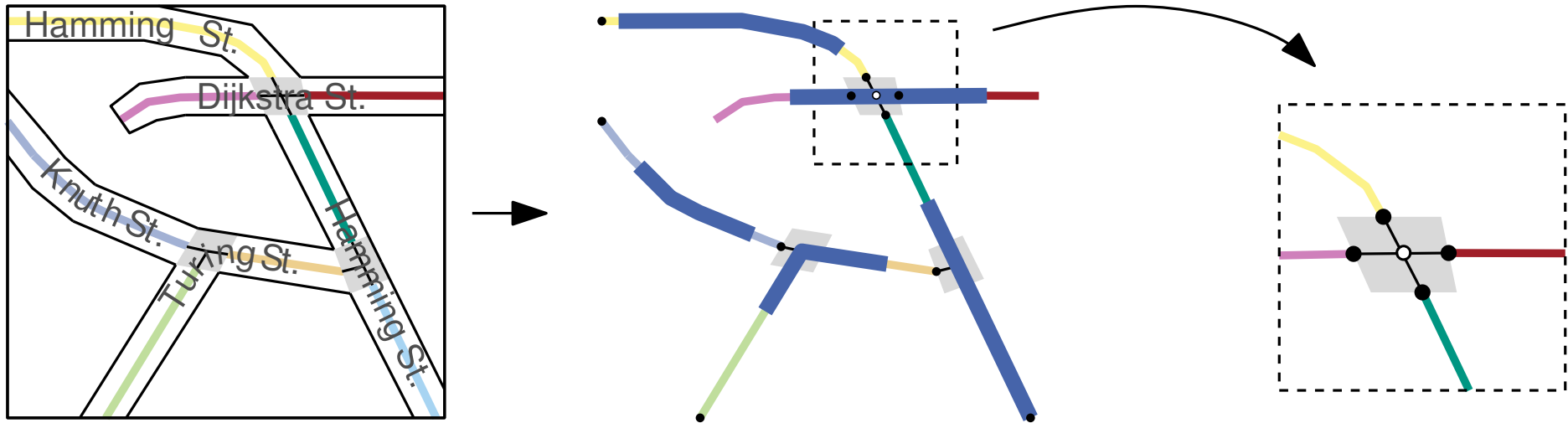
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Model labels as subcurves of the edges.

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Open problem: (dynamic) road labeling



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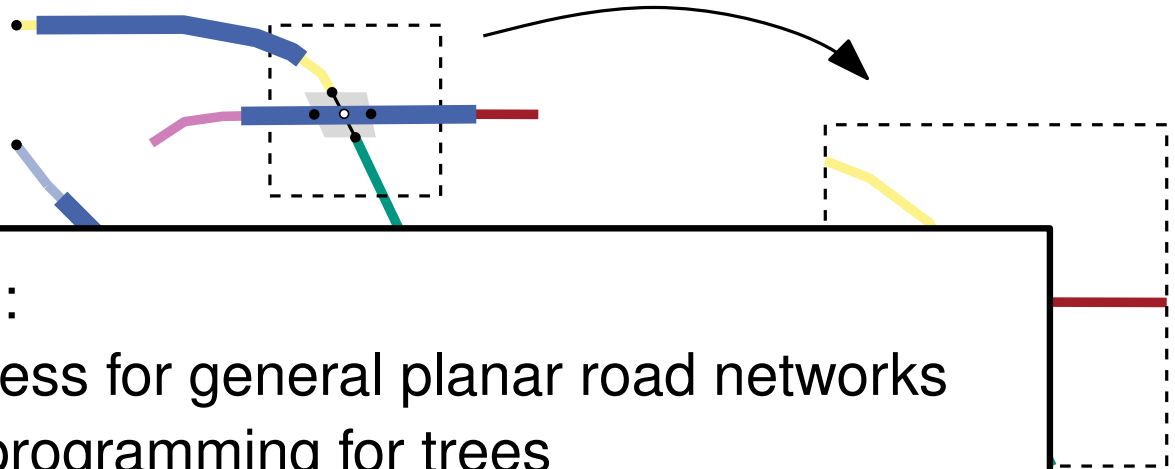
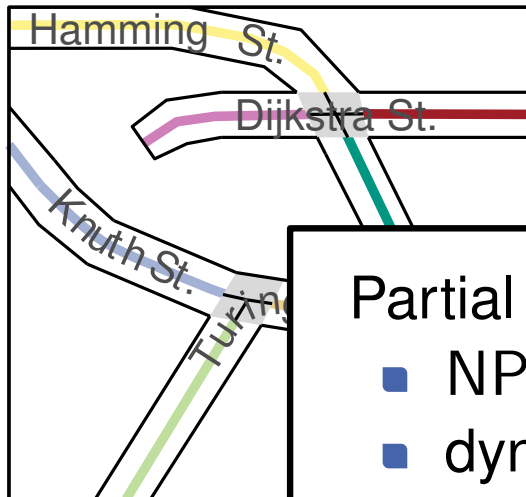
Model labels as subcurves of the edges.

- Labels must not end on junctions



Objectives: Maximize number of labeled road sections.
Minimize label movement when zooming.

Open problem: (dynamic) road labeling



Partial results:

- NP-hardness for general planar road networks
- dynamic programming for trees
- real-world road networks can be decomposed into many trees
- zooming support still ongoing research

Model road

- Each
- *Junc*

Model labels as subcurves of the edges.

- Labels must not end on junctions



Objectives: Maximize number of labeled road sections.
Minimize label movement when zooming.